

wi4243AP: Complex Analysis

week 8, Monday

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Delft, 20 october, 2014

Outline

- 1 A question from www.wisfaq.nl
- 2 My favourite formula
- 3 A moving string/belt

The question

<http://www.wisfaq.nl/show3archive.asp?id=60954&j=2009>
I have following integral

$$\int_0^{\infty} \frac{dx}{\sqrt{x}(x^2 + 1)}$$

Sing points in the upper half plane are $x = i$ (pole order 1) and $x = 0$ (pole order 1/2).

I can rewrite the integral:

$$\int_{+} f(z) dz = 2\pi i \operatorname{Res}(f, i) = \int_{-R}^{-\epsilon} \dots + \int_{\gamma_{\epsilon}} \dots + \int_{\epsilon}^R \dots + \int_{\gamma_R}$$

The question

The second and fourth integral (on the right-hand side) tend 0
(can be proved via an estimate, I did that WAS OK.

If I want to calculate the given integral then I have

$$2\pi i \operatorname{Res}(f, i) = \frac{\pi}{\sqrt{i}} = \int_{-\infty}^0 \frac{dx}{\sqrt{x}(x^2+1)} + \int_0^{\infty} \frac{dx}{\sqrt{x}(x^2+1)}$$

My problem now is: How do I get the desired integral

$$\int_0^{\infty} dx/\sqrt{x}(x^2+1)$$

Well ... ?

Answer

- $\sqrt{i} = \frac{1}{2}\sqrt{2} + \frac{i}{2}\sqrt{2}$ and so $\pi/\sqrt{i} = \frac{\pi}{2}\sqrt{2} - i\frac{\pi}{2}\sqrt{2}$
- For $x < 0$ we have $\sqrt{x} = i\sqrt{|x|}$ so $\int_{-\infty}^0$ becomes $-i \int_0^{\infty}$

We get

$$\int_0^{\infty} \frac{dx}{\sqrt{x}(x^2 + 1)} = \frac{\pi\sqrt{2}}{2}$$

One of Euler's best

$$\sum_{n=1}^{\infty} \frac{1}{n^2} = \frac{\pi^2}{6}$$

A useful function and contour

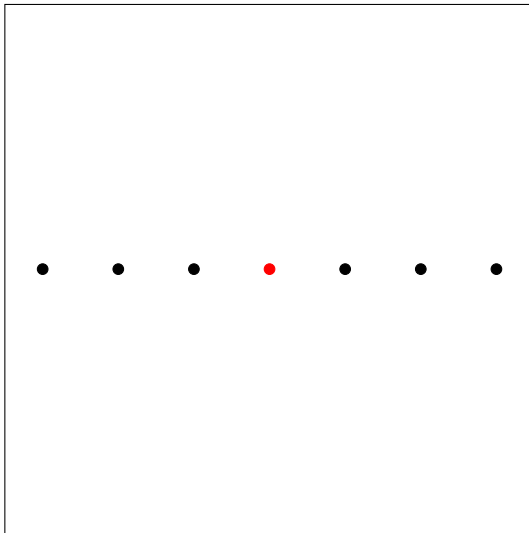
We use

$$f(z) = \frac{\pi \cos \pi z}{z^2 \sin \pi z}$$

and large squares for contours.

Γ_N is the square with vertices $(\pm 1 \pm i)(N + \frac{1}{2})$.

Here's Γ_3



The contour Γ_3

Pole of order 3
at 0

Poles of order 1
at all nonzero
integers

Residues

The residues at nonzero n are easy:

$$\text{Res}(f, n) = \frac{\pi \cos \pi n}{n^2 \pi \cos \pi n}$$

Pole of order 1, so we substitute n in

$$\frac{\pi \cos \pi z}{z^2 (\sin \pi z)'}$$

Residues

We calculate a few terms of the Laurent series of $\frac{\cos z}{\sin z}$:

$$\left(\frac{a_{-1}}{z} + a_0 + a_1z + \dots\right)\left(z - \frac{1}{6}z^3 + \dots\right) = 1 - \frac{1}{2}z^2 + \dots$$

or

$$a_{-1} + a_0z + \left(a_1 - \frac{1}{6}a_{-1}\right)z^2 + \dots = 1 - \frac{1}{2}z^2 + \dots$$

so: $a_{-1} = 1$, $a_0 = 0$, $a_1 = -\frac{1}{2} + \frac{1}{6}a_{-1} = -\frac{1}{3}$.

Residues

We find

$$f(z) = \frac{\pi}{z^3} - \frac{\pi^2}{3} \frac{1}{z} + \dots$$

and so

$$\operatorname{Res}(f, 0) = -\frac{\pi^2}{3}$$

The integrals

We find that, for every N ,

$$2\pi i \oint_{\Gamma_N} f(z) dz = -\frac{1}{3}\pi^2 + 2 \sum_{n=1}^N \frac{1}{n^2}$$

Now we show

$$\lim_{N \rightarrow \infty} \oint_{\Gamma_N} f(z) dz = 0$$

Estimates

Length of Γ_N : $4 \times (2N + 1) = 8N + 4$.

On Γ_N we have $\frac{1}{z^2} \leq \frac{1}{N^2}$.

Remember:

$$|\cos z| = \sqrt{\sinh^2 y + \cos^2 x}$$

and

$$|\sin z| = \sqrt{\sinh^2 y + \sin^2 x}$$

Estimates

If $x = \pm(N + \frac{1}{2})$ then

$$|\cotan \pi z| = \frac{\sqrt{\sinh^2 \pi y}}{\sqrt{\sinh^2 \pi y + 1}} \leq 1$$

Estimates

If $y = \pm(N + \frac{1}{2})$ then

$$\begin{aligned} |\cotan \pi z| &= \frac{\sqrt{\sinh^2 \pi(N + \frac{1}{2}) + \cos^2 \pi x}}{\sqrt{\sinh^2 \pi(N + \frac{1}{2}) + \sin^2 \pi x}} \\ &\leq \frac{\sqrt{\sinh^2 \pi(N + \frac{1}{2}) + 1}}{\sqrt{\sinh^2 \pi(N + \frac{1}{2})}} \\ &\leq 2 \end{aligned}$$

(when $N \geq 1$).

Finishing up

Everything combined:

$$\left| \oint_{\Gamma_N} f(z) dz \right| \leq \frac{(8N + 4) \times \pi \times 2}{N^2}$$

which suffices to have the limit be equal to zero.

A differential equation

A string or belt runs on two wheels one unit apart at a speed of v units.

The function $w(x, t)$ describes the lateral displacement of the string at position x ($0 < x < 1$) and time t ($t > 0$).

It satisfies the following (partial) differential equation

$$\frac{\partial^2 w}{\partial t^2} + 2v \frac{\partial^2 w}{\partial x \partial t} + (v^2 - 1) \frac{\partial^2 w}{\partial x^2} = 0$$

If $v = 0$ then we have the wave equation.

Boundary conditions

We impose boundary conditions:

$$w(0, t) = 0 \text{ and } w(1, t) = f(t)$$

One wheel is stable, the other one wiggles a bit.

We start at rest:

$$w(x, 0) = 0 \text{ and } w_t(x, 0) = 0 \text{ and } w_x(x, 0) = 0$$

Apply Laplace transform

Transform the equation:

$$s^2 W(x, s) - s \cdot w(x, 0) - w_t(x, 0) + 2v(sW_x(x, s) - w_x(x, 0)) \\ + (v^2 - 1)W_{xx}(x, s) = 0$$

this can be rewritten as

$$W_{xx} + \frac{2vs}{v^2 - 1} W_x + \frac{s^2}{v^2 - 1} W = 0.$$

Note: linear with constant coefficients

Solve the differential equation

Characteristic equation:

$$\lambda^2 + \frac{2vs}{v^2 - 1}\lambda + \frac{s^2}{v^2 - 1} = 0$$

with solutions

$$\lambda_1 = \frac{-s}{v + 1} \quad \text{and} \quad \lambda_2 = \frac{-s}{v - 1}$$

Hence

$$W(x, s) = C_1(s)e^{\lambda_1 x} + C_2(s)e^{\lambda_2 x}$$

The 'constants' C_1 and C_2 depend on s .

C_1 and C_2

$W(0, s) = 0$, hence $C_1(s) + C_2(s) = 0$.

$W(1, s) = F(s)$ (transform of f), hence $C_1(s)(e^{\lambda_1} - e^{\lambda_2}) = F(s)$

and so $C_1(s) = \frac{F(s)}{e^{\lambda_1} - e^{\lambda_2}}$.

We get

$$W(x, s) = F(s) \cdot \underbrace{\frac{\exp\left(\frac{-sx}{v+1}\right) - \exp\left(\frac{-sx}{v-1}\right)}{\exp\left(\frac{-s}{v+1}\right) - \exp\left(\frac{-s}{v-1}\right)}}_{H(x, s)}$$

If we can find the inverse transform, $h(x, t)$, of $H(x, s)$ then we are done:

$$w(x, t) = f(t) * h(x, t) = \int_0^t f(\tau) h(x, t - \tau) d\tau$$

Inversion

Unfortunately $H(x, s)$ has many singularities: the solutions to

$$\exp\left(\frac{-s}{v+1}\right) = \exp\left(\frac{-s}{v-1}\right)$$

or

$$\exp\left(\frac{2s}{v^2-1}\right) = 1$$

these are $s_n = (v^2 - 1)n\pi i$, with $n \in \mathbb{Z}$.

$s_0 = 0$ is a removable singularity, all others are poles of order 1.

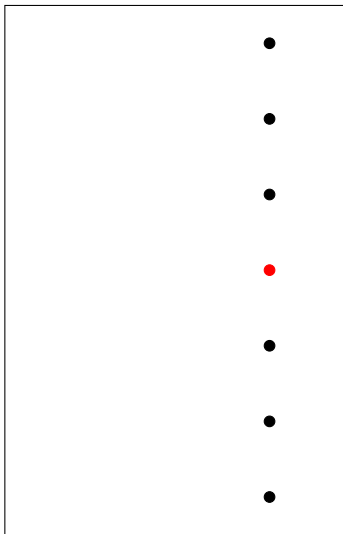
Inversion formula

We know that

$$h(x, t) = \frac{1}{2\pi i} \lim_{R \rightarrow \infty} \int_{1-iR}^{1+iR} H(x, s) e^{st} ds$$

As we have infinitely many singularities we have no annulus; we can try a trick like with my favorite formula.

Inversion formula



The contour Γ_3

Removable
singularity
at 0

Poles of order 1
at $(v^2 - 1)n\pi i$

Slight problem

The integrals along the three other sides do not converge to 0. What is true is that $H(x, s)$ is bounded on those rectangles, provided the horizontals are at $\pm(n + \frac{1}{2})(v^2 - 1)\pi i$:
So, we divide by s^2 :

$$W(x, s) = (s^2 F(s) - sf(0) - f'(0)) \frac{H(x, s)}{s^2} + (sf(0) + f'(0)) \frac{H(x, s)}{s^2}$$

This makes inversion possible, at the cost of a more complicated convolution.

Note that 0 is now a pole of order 2.

Residues

We have

$$H(x, s) = \frac{\exp\left(\frac{-sx}{v+1}\right) - \exp\left(\frac{-sx}{v-1}\right)}{\exp\left(\frac{-s}{v+1}\right) - \exp\left(\frac{-s}{v-1}\right)}$$

At $s_n = (v^2 - 1)n\pi i$ we have $\frac{s_n}{v+1} = (v - 1)n\pi i$ and $\frac{s_n}{v-1} = (v + 1)n\pi i$ and so

$$\operatorname{Res}(H(x, s), s_n) = \frac{\exp(-x(v - 1)n\pi i) - \exp(-x(v + 1)n\pi i)}{-\frac{1}{v+1} \exp(-(v - 1)n\pi i) + \frac{1}{v-1} \exp(-(v + 1)n\pi i)}$$

Residues

The denominator becomes ($e^{n\pi i} = (-1)^n$):

$$(-1)^n e^{-vn\pi i} \left(-\frac{1}{v+1} + \frac{1}{v-1} \right) = \frac{(-1)^n 2e^{-vn\pi i}}{v^2 - 1}$$

We find

$$\begin{aligned} \operatorname{Res} \left(\frac{H(x, s)}{s^2} e^{st}, s_n \right) &= \frac{\exp(-x(v-1)n\pi i) - \exp(-x(v+1)n\pi i)}{(-1)^{n+1} 2n^2 \pi^2 (v^2 - 1) e^{-vn\pi i}} e^{s_n t} \\ &= \frac{(-1)^{n+1} e^{vn\pi i} e^{s_n t} (e^{-x(v-1)n\pi i} - e^{-x(v+1)n\pi i})}{2n^2 \pi^2 (v^2 - 1)} \end{aligned}$$

where $e^{s_n t} = e^{t(v^2-1)n\pi i}$

Residues

Finally, at 0 the residu that we need is the partial derivative $\frac{\partial}{\partial s} H(x, s)e^{st}$ evaluated at 0. This comes out as

$$\frac{x}{v^2 - 1} (v - xv + t(v^2 - 1))$$

Now collect everything in one giant sum.

The final form

We get the inverse transform of $H(x, s)/s^2$:

$$\frac{x}{v^2 - 1} (v - xv + t(v^2 - 1)) - \sum_{n \neq 0} \frac{(-1)^n e^{vn\pi i} e^{snt} (e^{-x(v-1)n\pi i} - e^{-x(v+1)n\pi i})}{2n^2\pi^2(v^2 - 1)}$$

For more details see the original paper (link on BlackBoard).

What to do?

Now go forth and study!